

**ONE-SIDE-ELECTRODE-TYPE FLUIDIC SENSING MECHANISM
INSPIRED FROM FISH CUPULA**

MOHD NORZAIDI BIN MAT NAWI

UNIVERSITI SAINS MALAYSIA

2015

**ONE-SIDE-ELECTRODE-TYPE FLUIDIC SENSING MECHANISM
INSPIRED FROM FISH CUPULA**

by

MOHD NORZAIDI BIN MAT NAWI

**Thesis submitted in fulfillment of the requirements
for the degree of
Doctor of Philosophy**

April 2015

ACKNOWLEDGEMENTS

In preparing this thesis, I was in contact with many peoples, researchers, academicians, and practitioners. They have contributed towards my understanding and thoughts. In particular, I wish to express my sincere appreciation to my main project supervisor, Dr. Asrulnizam Abd Manaf, for encouragement, guidance, critics and friendship. I am also very thankful to my co-supervisors Associate Prof Dr. Mohd Rizal Arshad and Prof Dr. Othman Sidek for their guidance, advices and motivation. Without their continued support and interest, this thesis would not have been the same as presented here.

I am also indebted to Universiti Sains Malaysia (USM) for funding this research as well as living expenses through various grants, allowances and incentives. Librarians at USM and fellows at Nanofabrication and Functional Materials (NFM) research group of School of Mechanical Engineering also deserve special thanks for their assistance in supplying the relevant literatures and expertise.

My fellow peers of Underwater Robotic Research Group (URRG), USM should also be recognized for their support. My sincere appreciation also extends to all my colleagues and others who have provided assistance at various occasions. Their views and tips are useful indeed. Unfortunately, it is not possible to list all of them in this limited space. I am grateful to all my family members as well for their continuous support.

TABLE OF CONTENTS

	Page
ACKNOWLEDGEMENTS	ii
TABLE OF CONTENTS	iii
LIST OF TABLES	viii
LIST OF FIGURES	ix
LIST OF ABBREVIATIONS	xv
LIST OF SYMBOLS	xvii
ABSTRAK	xx
ABSTRACT	xxii

CHAPTER 1 – INTRODUCTION

1.1	Background	1
1.2	Problem Statements	4
1.3	Research Objectives	6
1.4	Research Scope	6
1.5	Summary of Contributions	8
1.6	Organization of Thesis	9

CHAPTER 2 - LITERATURE REVIEW

2.1	Introduction	11
2.2	The Nature of Fish Lateral Line System	11
2.3	Overview on Flow Sensors	13
2.4	Design Evolution and Principle of Flow Detection	16
2.5	Material Used and Fabrication Process	20

2.6 Sensor Characterization	26
2.7 Microfluidic Based Sensors	30
2.8 Electrical Double Layer Theory.....	33
2.9 Numerical Analysis	34
3.0 Summary	36

CHAPTER 3 - METHODOLOGY: THEORY AND IMPLEMENTATION

3.1 Introduction	38
3.2 Sensor Design and Principle.....	40
3.2.1 Design Structure Evolution	40
3.2.2 Sensor Design Inspired from Fish Cupula	45
3.2.3 Sensor Principle.....,	48
3.2.4 Sensor Design for Fluidic Based Pressure Sensor	50
3.2.5 Liquid Selection for Microchannel.....	51
3.3 CFD Simulation Method	53
3.3.1 Flow Analysis on Structure using ANSYS Fluent	54
3.3.2 Geometry Setup	55
3.3.3 Grid Generation	56
3.3.4 Boundary Condition	57
3.3.5 Microchannel Analysis Procedure	58
3.4 FEA Simulation Method	59
3.4.1 Structural Analysis using ANSYS Mechanical APDL	60
3.4.2 Geometry Construction and Mesh Generation	60
3.4.3 Define Loads	61
3.5 Sensors Fabrication	62

3.5.1	Dome-Shaped Membrane Container	63
3.5.2	Dome-Shaped Membrane Container Using Stamping Technique ...	66
3.5.3	Flat Membrane Container	68
3.5.4	Electrode Printing	69
3.5.5	Sealing Process	70
3.5.6	Wire Bonding and Injection Process.....	71
3.6	System Integration	71
3.7	Characterization Method for Fluidic Based Pressure Sensor.....	72
3.7.1	Electrical Double Layer Behaviour	73
3.7.2	Pressure Measurement Setup	74
3.7.3	Vibration Analysis Setup	74
3.7.4	Temperature Analysis Setup	76
3.7.5	Lifetime Analysis Procedure	77
3.8	Characterization Method for Fluidic Based Flow Sensor.....	77
3.8.1	Flow Measurement Setup	78
3.8.2	Directionality Test Setup	80
3.8.3	Experimental Setup for Moving Object Detection	81
3.8	Summary	81

CHAPTER 4 – RESULTS AND DISCUSSIONS

4.1	Introduction	82
4.2	Simulation Results.....	82
4.2.1	Flow Analysis on the Hair Cell and Dome Structure	83
4.2.2	Performance Evaluation of Dome-Shaped Membrane	91
4.2.3	Selection of Liquid	95

4.3	Fabrication of Dome-Shaped Membrane Container	98
4.3.1	Fabrication Effect and Its Performance Evaluation Using FEA	98
4.3.2	Modification of Fabrication Process	103
4.3.3	Fabrication Limitation	105
4.4	Fluidic Based Pressure Sensor Characterization	106
4.4.1	Selection of Liquid	106
4.4.2	Validation for Fluid Mechanism.....	107
4.4.3	Operating Frequency	111
4.4.4	Linearity and Hysteresis for Pressure Measurement	113
4.4.5	Vibration Effect	116
4.4.6	Temperature Effect	118
4.4.7	Lifetime of Sensor	119
4.5	Fluidic based Flow Sensor Characterization	120
4.5.1	Operating Frequency	120
4.5.2	Water Effect.....	121
4.5.3	Response Time	122
4.5.4	Water Flow Measurement and Hysteresis	123
4.5.5	Directionality Test	125
4.5.6	Moving Object Detection	128
4.5.7	Vibration Effect	129
4.6	Summary	131

CHAPTER 5 – CONCLUSIONS & RECOMMENDATIONS

5.1	Conclusions	133
5.2	Recommendations	134

REFERENCES	136
APPENDICES	147
LIST OF PUBLICATIONS	156

LIST OF TABLES

		Page
Table 2.1	Various materials and fabrications of the bio-inspired flow sensor	24
Table 2.2	Various flow characterization of the bio-inspired flow sensor	29
Table 3.1	Mechanical properties of PDMS, PI and PU	45
Table 3.2	List of liquids for microchannel	52
Table 4.1	Drag force for variation of leading edge distance	91
Table 4.2	Minimum and maximum range of membrane thickness for 5 samples	99
Table 4.3	Parameters for the fabricated dome-shaped membrane	99
Table 4.4	The calculation of capacitance value	113

LIST OF FIGURES

	Page
Figure 1.1	3
Figure 2.1	12
(a) Distribution of lateral line.	
(b) Cross sectional of a canal. (c) Superficial neuromasts	
Figure 2.2	14
Figure 2.3	17
(a) The flow sensor inspired from lateral line flow sensor (Fan <i>et al.</i> , 2002). (b) Hair cell fabricated using SU-8 material (Nguyen <i>et al.</i> , 2010)	
Figure 2.4	17
The vertical hair cell that installed with strain gauge (Chen <i>et al.</i> , 2003)	
Figure 2.5	18
Polyurethane polymer based hair cell (Engel <i>et al.</i> , 2005b)	
Figure 2.6	19
Schematic diagram for capacitive hair sensors (Jaganatharaja <i>et al.</i> , 2009)	
Figure 2.7	19
Free standing cantilever for flow sensor (Wang <i>et al.</i> , 2007)	
Figure 2.8	20
(a) Schematics of hair cell sensor capped with hydrogel cupula (b) hydrogel cupula fabricated on the hair cell (Paleshanko <i>et al.</i> , 2007).	
Figure 2.9	27
Resistance versus flow rate under constant voltage (Fan <i>et al.</i> , 2002)	
Figure 2.10	27
Output response for variation of water flow direction (a) Linear plot. (d) Polar plot (Chen <i>et al.</i> , 2007)	
Figure 2.11	32
Figure 2.11: (a) The illustration for PDMS microchannel, (b) Coplanar electrode design for micro droplet detection (Elbuken <i>et al.</i> , 2011)	

Figure 2.12	(a) The electrodes pattern, (b) cross-sectional structure view A-A'(Manaf <i>et al.</i> , 2007)	32
Figure 3.1	Methodology framework which was divided into three phases	39
Figure 3.2	Flow chart for design process	42
Figure 3.3	Rectangular-shaped hair cell	43
Figure 3.4	Cylinder-shaped hair cell	43
Figure 3.5	Dome-shaped structure	43
Figure 3.6	(a) Schematic diagram of the flow sensor; (b) Cross section A-A' for formation of ionic layer	47
Figure 3.7	The fabricated fluidic based flow sensor	47
Figure 3.8	The Sensor Principle (a) Cross-sectional area of the sensor. (b) Sensor pattern for no flow rate and after applied flow rate condition	49
Figure 3.9	Schematic diagram of the pressure sensor	50
Figure 3.10	Sensor pattern for no load and applied pressure condition	51
Figure 3.11	CFD simulation procedures	53
Figure 3.12	The illustration for directionality test by varying the flow direction and flow angle.	54
Figure 3.13	The geometry model in ANSYS Fluent	55
Figure 3.14	(a) Computational domain (b) Dome and bottom domain	57
Figure 3.15	The computational model for microchannel	59
Figure 3.16	FEA simulation procedures	60
Figure 3.17	Cross sectional of dome for FEA analysis	61
Figure 3.18	The 3D meshed structure of dome	62
Figure 3.19	Simple fabrication process for fluidic based flow sensor.	63

Figure 3.20	Illustration for the fabrication of the dome-shaped container	65
Figure 3.21	Images showing (a) The mold was placed on the top of glass; (b) the container after peel off process.	65
Figure 3.22	Illustration for the fabrication of dome-shaped container using a stamping technique.	67
Figure 3.23	The fabricated molds for stamping technique.	67
Figure 3.24	Illustration for the fabrication of flat-shaped container	68
Figure 3.25	The images of (a) The mold placed on the petri dish (b) The flat membrane container after peeling process	69
Figure 3.26	(a) Design of electrode using software EAGLE 6.1.0. (b) Image of the electrode on the PCB board	69
Figure 3.27	The illustrations for the sealing process	70
Figure 3.28	The illustration for injection process using syringe.	71
Figure 3.29	The system integration for fluidic based sensor	72
Figure 3.30	Experimental procedures for fluidic based pressure sensor characterization	73
Figure 3.31	Model of capacitance (C_T)	73
Figure 3.32	(a) The diagram for the measurement setup (not to scale) (b) The image of measurement platform	74
Figure 3.33	Schematic diagram for vibration analysis setup	75
Figure 3.34	The image of measurement setup for vibration analysis	75
Figure 3.35	Schematic diagram for temperature analysis setup	76
Figure 3.36	The image of measurement setup for temperature analysis.	76
Figure 3.37	Experimental procedures for fluidic based flow sensor characterization	77

Figure 3.38	A schematic diagram for flow measurement setup	78
Figure 3.39	The image of (a) system measurement (b) flow measurement	79
Figure 3.40	Schematic drawing for directionality test setup	80
Figure 3.41	The picture of rotational stage for directionality test	80
Figure 3.42	Illustration for moving object passing the sensor	81
Figure 4.1	The pressure coefficient distribution for dome structure	84
Figure 4.2	The drag force acting on the dome surface for different radius of dome	85
Figure 4.3	The drag force acting on the hair cell for different flow direction, comparison between the rectangular and cylinder shape; Linear and Polar plot	87
Figure 4.4	The drag force acting on the hair cell for different flow angles, comparison between the rectangular and cylinder shape	88
Figure 4.5	The drag force acting on the dome- shaped for different flow direction; Polar plot	89
Figure 4.6	The drag force acting on the dome-shaped for different flow angle	89
Figure 4.7	(a) Schematic for leading edge. (b) The drag force acting on the dome surface for variation of leading edge	90
Figure 4.8	Deflection of PDMS dome-shaped membrane for radius of 3.2mm and thickness of 0.15mm at 25cm/s flow rate	92
Figure 4.9	Mises stress of PDMS dome-shaped membrane for radius of 3.2mm and thickness of 0.15mm at 25cm/s flow rate	92
Figure 4.10	The membrane deflection for variation of water flow rate, comparison between PDMS, Polyimide and Polyurethane	93
Figure 4.11	The membrane performance for different radius and thickness	

	(a) membrane deflection; (b) Mises stress	94
Figure 4.12	The velocity magnitude contours in microchannel. (a) x-y plane. (b) y-z plane	95
Figure 4.13	The average velocity for various heights of microchannel	96
Figure 4.14	The velocity profile for different electrolytes	97
Figure 4.15	SEM for the cross sectional of dome-shaped container	98
Figure 4.16	Membrane thickness for different samples	100
Figure 4.17	The cross sectional view of actual dome-shaped structure (a) SEM (b) CAD drawing	101
Figure 4.18	Deflection analysis at flow rate of 10cm/s for $t=0.15\text{mm}$	102
Figure 4.19	Deflection analysis of the ideal and modification shape of the dome membrane	102
Figure 4.20	The SEM for cross sectional of modified dome-shaped membrane	104
Figure 4.21	Flexible test for dome-shaped membrane, (a) push and (b) release condition.	104
Figure 4.22	The images for the dome-shaped fabrication, the membrane almost separated from the mold.	105
Figure 4.23	The cross sectional and fluid mechanism of the sensor	108
Figure 4.24	The top view of the microchannel	110
Figure 4.25	Pressure-liquid displacement inside microchannel, comparison between analytical and experimental.	111
Figure 4.26	The response in capacitance for different operating frequency, comparison between different types of liquid	113
Figure 4.27	The noises in output response for pressure down	114
Figure 4.28	Relationship between pressure up and pressure down	115

Figure 4.29	Direction of acceleration for horizontal and vertical direction	116
Figure 4.30	The vibration effect for horizontal and vertical (a) $\pm 1G$ and (b) $\pm 2G$	118
Figure 4.31	The temperature effect to the sensor performance	119
Figure 4.32	Lifetime effect of the fluidic based pressure sensor	120
Figure 4.33	The response in capacitance for different operating frequency, comparison between air and methanol.	121
Figure 4.34	Water effect in different environment, in air and water	122
Figure 4.35	The response time of the flow sensor	123
Figure 4.36	(a) Illustration for flow measurement setup. (b) Sensor response in capacitance, the experiment was repeated and error bars represented standard deviation error	124
Figure 4.37	The hysteresis for water flow measurement	125
Figure 4.38	Output response obtained for variation of water flow direction. (a) Linear plot. (b) Polar plot.	126
Figure 4.39	The leading edge at 180° flow direction	127
Figure 4.40	Output response for variation water of flow angle, linear plot	128
Figure 4.41	The sensor response for detecting moving object	129
Figure 4.42	The vibration effect for horizontal and vertical (a) $\pm 1G$ and (b) $\pm 2G$	130
Figure 4.43	The position of bubble inside dome-shaped membrane (a) Vertical (b) Horizontal	131

LIST OF ABBREVIATIONS

ADC	-	Analog to Digital Converter
APDL	-	Ansys Parametric Design Language
AUV	-	Autonomous Underwater Vehicle
Al	-	Aluminium
Au	-	Aurum/Gold
CAD	-	Computer-Aided Design
CB	-	Carbon Black
CFD	-	Computational Fluid Dynamic
Cr	-	Chromium
DOF	-	Degree Of Freedom
DMF	-	Dimethylformamide
EDLC	-	Electrical Double Layer Capacitor
EDM	-	Electric Discharge Machining
FEA	-	Finite Element Analysis
FSR	-	Force Sensitive Resistor
FR-4	-	Flame Retardant 4
INA	-	Instrumentation Amplifier
LCP	-	Liquid Crystal Polymer
LF	-	Low Frequency
LPCVD	-	Low-Pressure Chemical Vapour Deposition
MEMS	-	Micro-Electro-Mechanical Systems
MWNT	-	Multi-Walled Nanotubes
PEG	-	Polyethylene Glycol

PCB	-	Printed Circuit Board
PDMA	-	Plastic Deformation Magnetic Assembly
PDMS	-	Polydimethylsiloxane
PI	-	Polyimide
PU	-	Polyurethane
PVDF	-	Polyvinylidene Fluoride
PZT	-	lead Zirconium Titanate
RIE	-	Reactive-Ion Etching
RP	-	Rapid Prototype
SEM	-	Scanning Electron Microscope
Si	-	Silicon
UV	-	Ultraviolet

LIST OF SYMBOLS

A_s	-	Surface area of electrode
A_h	-	Surface area of hair cell
A_+	-	Surface area of sensing electrode
C_o	-	Common capacitance
C_+	-	Sensing capacitance
C_U	-	Capacitance change for pressure up
C_P	-	Capacitance change for pressure down
C_T	-	Total capacitance
C_D	-	Drag coefficient
D	-	Hydraulic diameter
d	-	Thickness of insulator
E	-	Young's Modulus
E_o	-	Bridge voltage
F_d	-	Drag force of hair cell
F_y	-	Drag force along vertical distance
F_{ym}	-	Vertical force for membrane
G	-	Gauge factor of strain gauge
I	-	Moment of inertia
L	-	Microchannel length
l	-	Length of hair cell
l_+	-	Length of sensing electrode
M	-	Moment of hair cell
p	-	Pressure of fluid

P	-	Pressure applied to the membrane
P_U	-	Pressure up
P_D	-	Pressure down
r_+	-	Radius of sensing electrode
Re	-	Reynold number
R_m	-	Radius of membrane
t	-	Thickness of hair cell
t_m	-	Thickness of membrane
t_c	-	Thickness of microchannel
u_y	-	Velocity along vertical distance
u_o	-	Applied flow rate
v	-	Fluid velocity
V_{avg}	-	Average flow velocity
V_{amp}	-	Amplifier voltage
V_{ref}	-	Reference voltage
$V_{membrane}$	-	Volume deflect by membrane
V_{liquid}	-	Volume deflect by liquid
w	-	Width of microchannel
w_+	-	Width of sensing electrode
W	-	Deflection of membrane
x	-	Leading edge distance
y	-	Vertical distance
μ	-	Dynamic viscosity
ΔC	-	Capacitance changes
ΔL	-	Liquid displacement

ΔP	-	Pressure difference
ρ	-	Density of water/fluid density
δ	-	Boundary layer thickness
ε	-	Strain estimation on hair cell
ε_0	-	Vacuum permittivity
ε_r	-	Dielectric constant of PDMS
η	-	Viscosity
ν	-	Poisson's ratio

MEKANISMA PENDERIAAN BENDALIR JENIS-ELEKTROD-SATU-SISI DIINSPIRASIKAN DARIPADA KUPULA IKAN

ABSTRAK

Penambahbaikan reka bentuk penderia berasaskan silikon direalisasikan dengan teknik fabrikasi kompleks yang mungkin mengurangkan keteguhan dan kebolehpercayaan penderia. Selain itu, kebanyakan penderia aliran semasa hanya mampu mengukur aliran dalam satu arah dan memerlukan lebih daripada satu penderia untuk meningkatkan keupayaan terutamanya untuk penderiaan pelbagai arah. Masalah-masalah ini boleh ditambah baik dengan menggunakan sistem bendalir untuk pengukuran aliran bawah air yang diinspirasi daripada mekanisme kupula pada badan ikan. Kupula menjadi pengantara daya-daya seretan dalam suasana sekeliling dan memindahkan pergerakan kepada sel-sel rambut untuk mendorong isyarat sel saraf. Reka bentuk penderia aliran yang dicadangkan dalam kajian ini terdiri daripada elektrod-satu-sisi dan membran berbentuk kubah yang diintegrasikan dengan saluran mikro. Apabila aliran mengenai membran, ia memberikan pesongan dan menganjak elektrolit di dalam saluran mikro. Elektrod, melalui lapisan penebat mengesan pergerakan elektrolit dan memberi perubahan dalam kemuatan. Dalam peringkat reka bentuk, simulasi telah dimulakan dengan memilih tiga jenis struktur termasuk bentuk segi empat tepat dan silinder sel rambut dan juga bentuk kubah. Struktur kubah didapati lebih sesuai untuk penderiaan pelbagai arah kerana struktur simetri yang membenarkan daya seretan yang tetap dari arah yang berbeza. Parameter membran berbentuk kubah seperti dimensi dan bahan-bahan telah diubah dan disimulasi. Disebabkan oleh mekanisme penderiaan baru, penderia tekanan yang mempunyai membran rata telah difabrikasi sebagai ujian awal. Kedua-dua membran berbentuk kubah dan membran rata telah difabrikasi menggunakan proses litografi lembut.

Kemudian, penderia tekanan berasaskan bendalir telah dicirikan berdasarkan kesan getaran dan suhu. Ujian kebolehpercayaan penderia tekanan untuk getaran dan suhu telah menunjukkan ralat pengukuran penderia ialah 3% oleh getaran lebih 25 Hz pada pecutan $\pm 2G$ dan 4%, untuk julat suhu daripada 10 hingga 50°C. Untuk pencirian penderia aliran berasaskan bendalir, frekuensi operasi dan masa tindak balas masing-masing adalah 1.2 kHz dan 0.35 s. Penderia ini dapat mengukur kadar aliran serendah 10 cm/s di dalam air, dengan resolusi 5 cm/s. Ujian berarahan menunjukkan bahawa penderia itu mampu untuk mengesan aliran dalam pelbagai arah dan sudut yang berbeza, di samping dapat mengesan objek bergerak pada jarak dekat.

ONE-SIDE-ELECTRODE-TYPE FLUIDIC SENSING MECHANISM INSPIRED FROM FISH CUPULA

ABSTRACT

Enhancement of silicon-based sensor designs is often realized using complex fabrication techniques which may reduce the robustness and reliability of the sensor. Also, most current flow sensors are only capable of measuring in one direction, requiring more than one sensor to improve capability, especially for multidirectional sensing. These problems may be enhanced using a fluidic system for underwater flow measurement, as inspired from the cupula mechanism on fish bodies. A cupula mediates the drags forces in the surrounding environment and transfers the movements into hair cells to induce the neuron signals. The proposed flow sensor design in this research consists of a one-side-electrode and dome-shaped membrane integrated with a microchannel. When the flow hits the membrane, it provides deflection and displaces the electrolyte inside the microchannel. The electrode, via its insulator layer senses the movement of the electrolyte and gives a change in capacitance value. During the design stage, the simulation was started by selecting three types of structure, including rectangular and cylinder shape of hair cell and also the dome-shaped. The dome structure has been found to be more suitable for multidirectional sensing due to its symmetry structure, which allows the constant drag force from different directions. Dome-shaped membrane parameters such as dimension and materials were varied and simulated. Due to the new sensing mechanism, the pressure sensor that has flat membrane was fabricated as a preliminary test. Both a dome-shaped membrane and flat membrane were fabricated using the soft lithography process. Then, a fluidic based pressure sensor was characterized based on vibration and temperature effect. A reliability test for the

pressure sensor for vibration and temperature has demonstrated that the sensor measurement error was 3% by vibration over 25 Hz at acceleration $\pm 2G$ and 4%, for a temperature range from 10 to 50°C. For the fluidic based flow sensor characterization, operating frequency and time response were 1.2 kHz and 0.35 s, respectively. This sensor was able to measure the flow rate at rates as low as 10 cm/s in water, with a resolution of 5 cm/s. The directionality test has shown that the sensor is capable of detecting flow in different direction and angle, while also being able to detect a moving object at close range.